

Exact and efficient simulation of photon quantum interference using tensor train decomposition

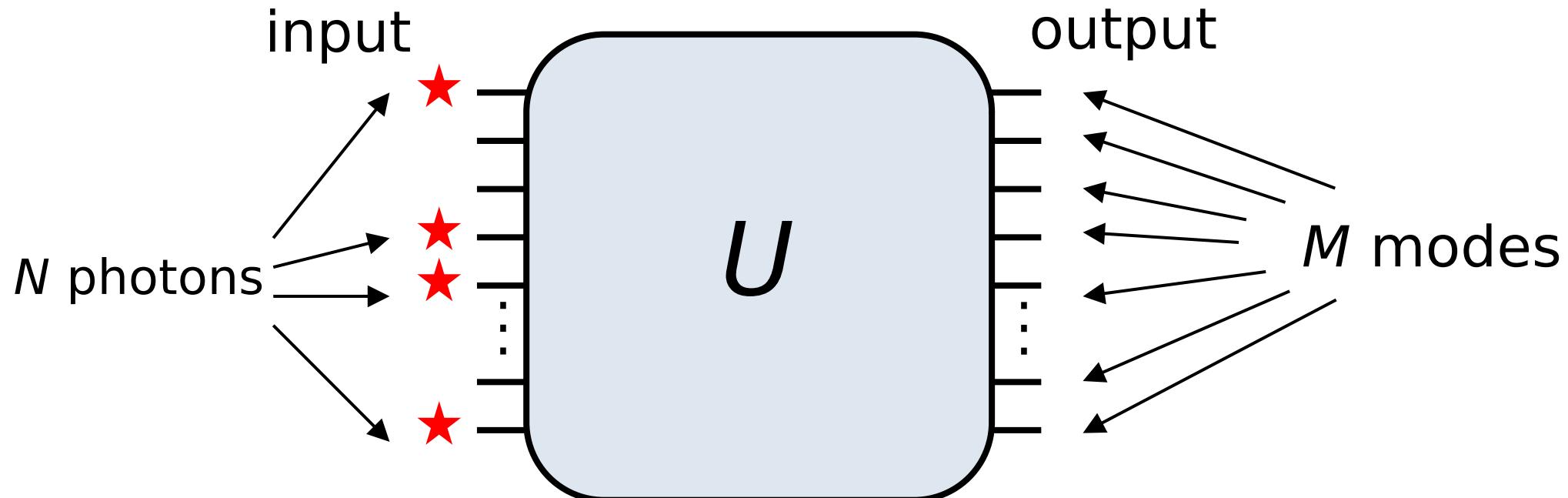
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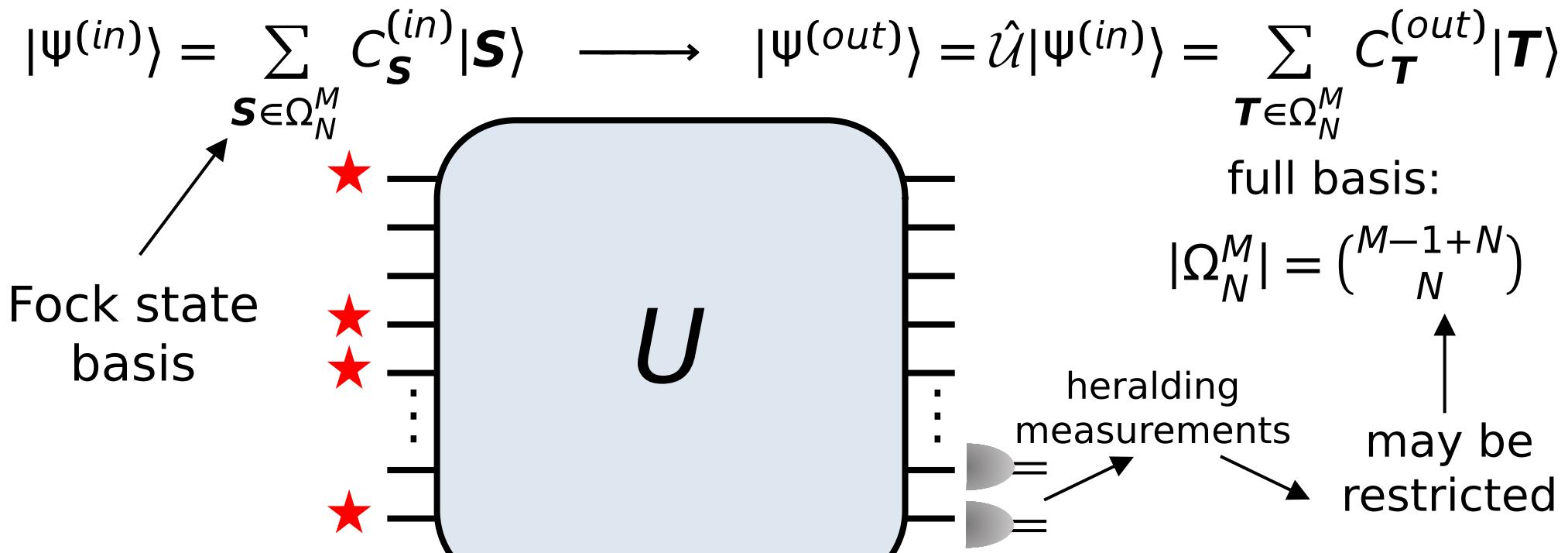
Russian Supercomputing Days 2024
September 24

Problem under consideration

A standard setup of linear optical quantum computation



Problem under consideration



The task: precisely compute $C_{\mathbf{T}}^{(out)}$ for a lot of different U

Fock state

occupation numbers

assignment list: $1 \leq s_1 \leq s_2 \leq \dots \leq s_N \leq M$

$$|\mathbf{S}\rangle = |S_1, S_2, S_3, \dots, S_M\rangle = |\mathbf{s}\rangle = |\{s_1, s_2, s_3, \dots, s_N\}\rangle$$

S_i photons
in mode i

$$\sum_{i=1}^M S_i = N$$

“ i -th photon
in mode s_i ”

$$\sum_{j=1}^N \delta_{is_j} = S_i$$

full basis:

$$|\Omega_N^M| = \binom{M-1+N}{N}$$

examples:

$$|1,2,0,1\rangle = |\{1, 2, 2, 4\}\rangle$$

$$|0,2,4\rangle = |\{2, 2, 3, 3, 3\}\rangle$$

Fock operators

$$\Omega_N^M \xrightarrow{\hat{a}_i^\dagger} \Omega_{N+1}^M \quad \begin{matrix} \text{creation} \\ \text{operator} \end{matrix} \quad [\hat{a}_i, \hat{a}_j^\dagger] = \delta_{ij} \quad \Omega_N^M \xrightarrow{\hat{a}_i} \Omega_{N-1}^M \quad \begin{matrix} \text{annihilation} \\ \text{operator} \end{matrix}$$

Definition: $[\hat{a}_i, \hat{a}_j] = 0, [\hat{a}_i^\dagger, \hat{a}_j^\dagger] = 0$

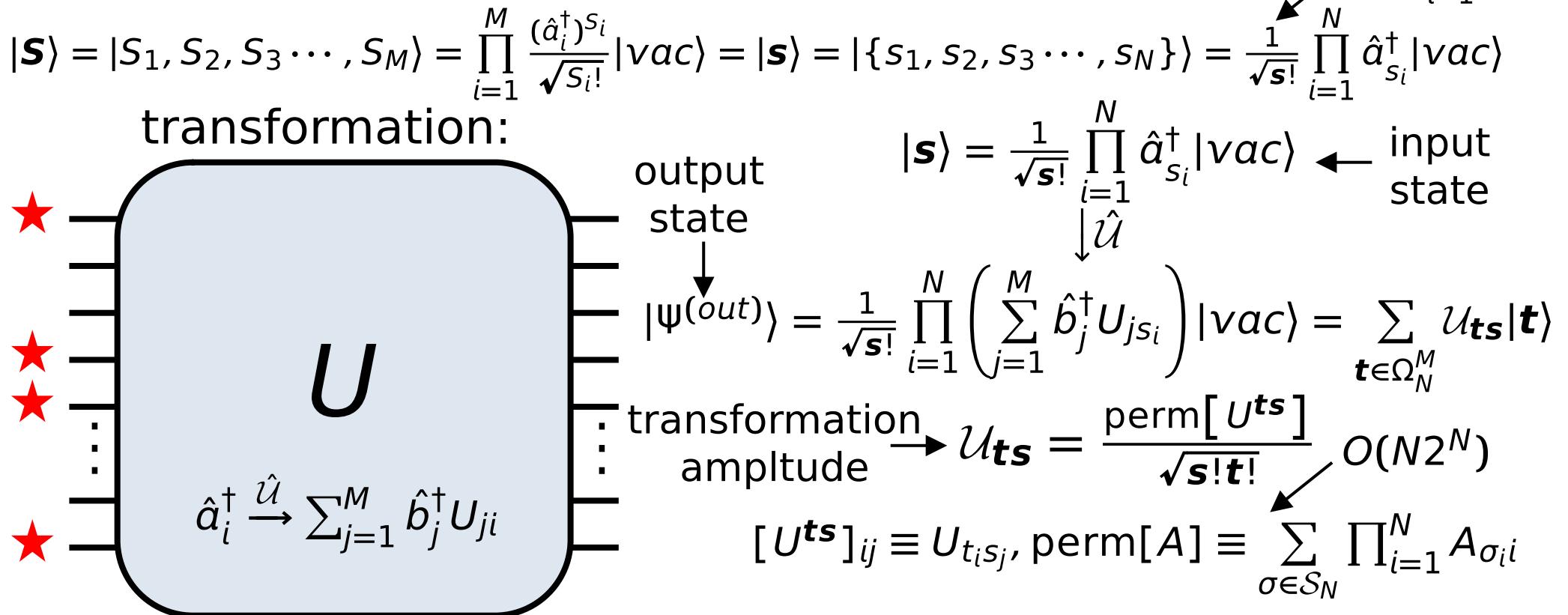
$$\hat{a}_i^\dagger | \dots, S_i, \dots \rangle = \sqrt{S_i + 1} | \dots, S_i + 1, \dots \rangle \quad \hat{a}_i | \dots, S_i, \dots \rangle = \sqrt{S_i} | \dots, S_i - 1, \dots \rangle$$

$$\hat{a}^\dagger = \begin{pmatrix} 0 & 0 & \dots & & \\ 1 & 0 & \dots & & \\ 0 & \sqrt{2} & \dots & & \\ \vdots & \vdots & \ddots & \vdots & \\ & \dots & \sqrt{K} & 0 & \\ & \dots & 0 & \sqrt{K+1} & \end{pmatrix} \uparrow \Omega_{K+1}^1$$

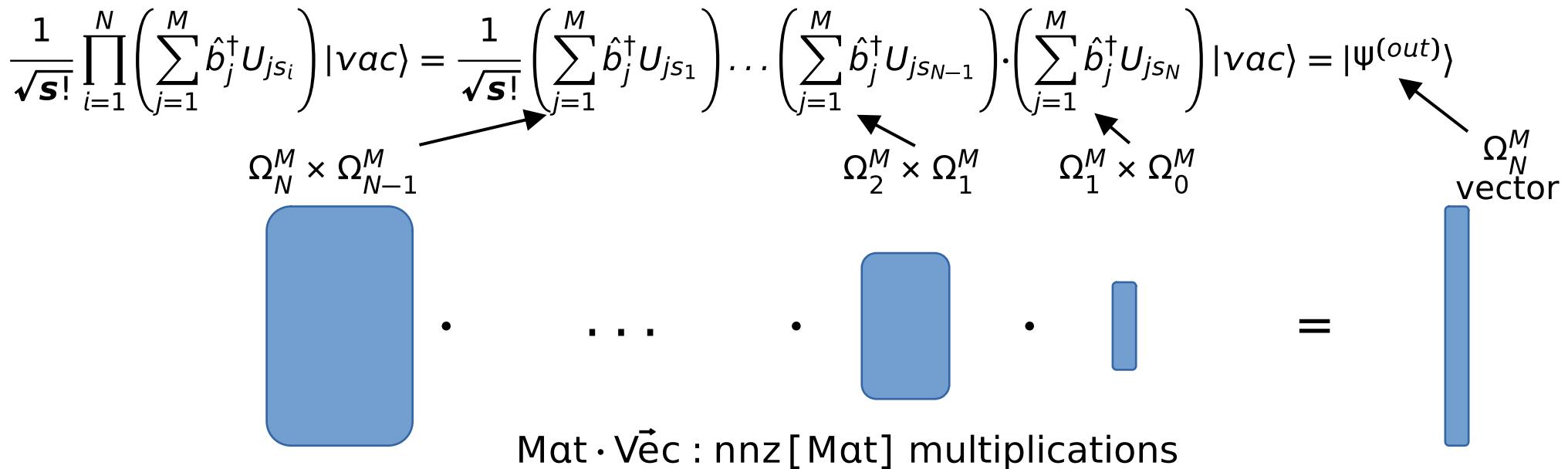
$$\hat{a} = \begin{pmatrix} 0 & 1 & 0 & \dots & & \\ 0 & 0 & \sqrt{2} & \dots & & \\ \vdots & \vdots & \vdots & \ddots & \vdots & \\ & \dots & & \sqrt{K-1} & 0 & \sqrt{K} \\ & \dots & 0 & \sqrt{K} & \vdots & \vdots \end{pmatrix} \uparrow \Omega_{K-1}^1$$

very sparse

Fock state evolution



SLOS method



Matrices have a lot of zeroes — total complexity of a problem is $O(N(\frac{M-1+N}{N}))$

Generalization to arbitrary set of input and output Fock bases is unclear

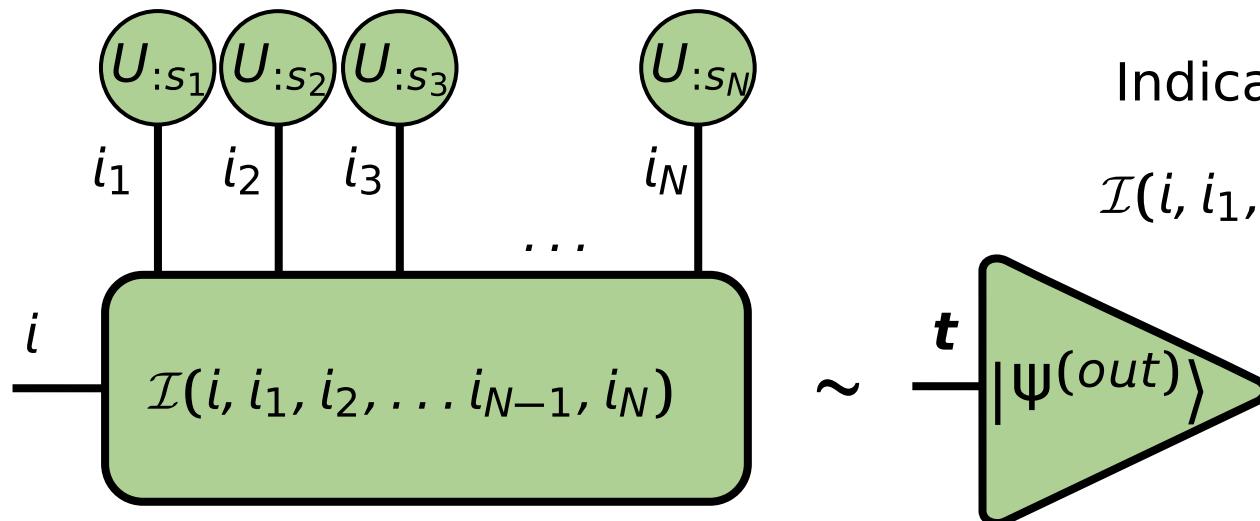
TT decomposition

may not be a full basis

Suppose output basis is given by a set of assignment lists: $L[i] = \{t_1, t_2, \dots, t_N\}$

A key observation:

$$\text{perm}[U^{\mathbf{ts}}] = \sum_{\sigma \in S_N} \prod_{j=1}^N U_{t_{\sigma_j} s_j} \stackrel{\mathbf{t}=L[i]}{=} \mathbf{t}! \sum_{i_1=1}^M \sum_{i_2=1}^M \cdots \sum_{i_N=1}^M \mathcal{I}(i, i_1, i_2, \dots, i_N) \prod_{k=1}^N U_{i_k s_k}$$

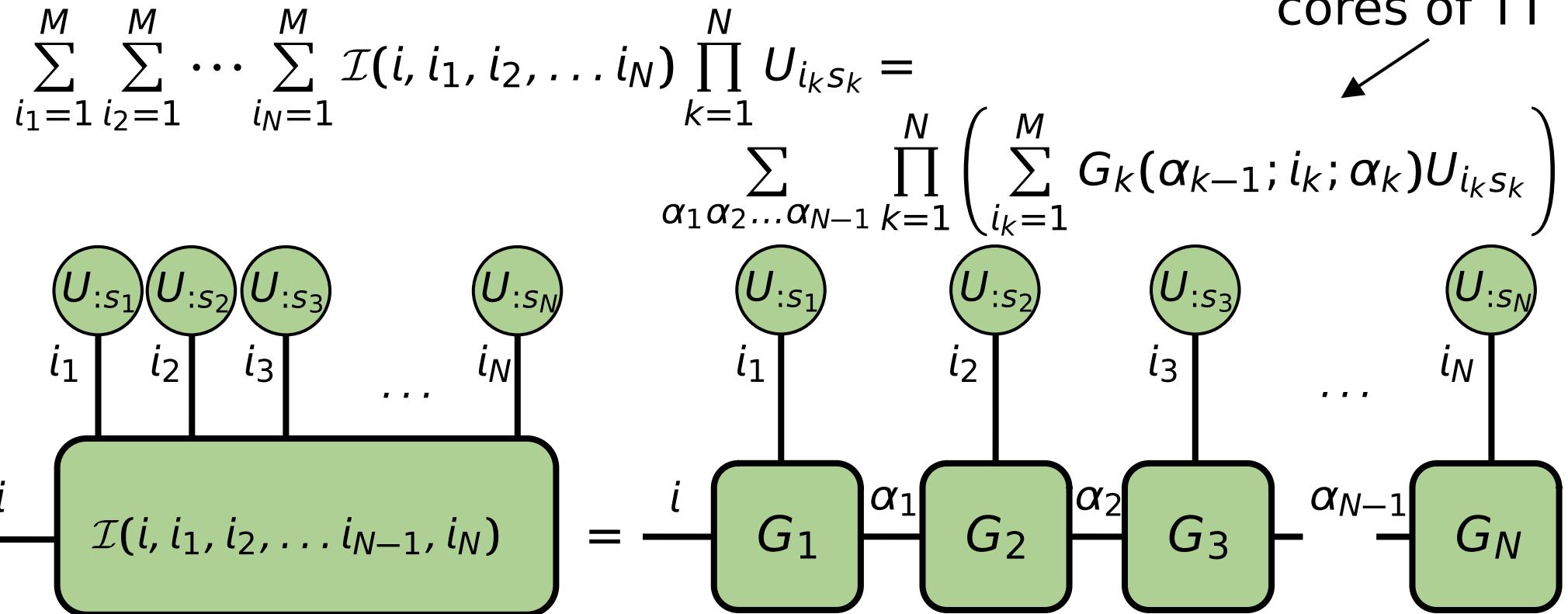


Indicator tensor:

$$\mathcal{I}(i, i_1, \dots, i_N) = \begin{cases} 1, & \{i_1, \dots, i_N\} = L[i] \\ 0, & \text{otherwise} \end{cases}$$

\mathcal{I} is completely defined by L

TT decomposition



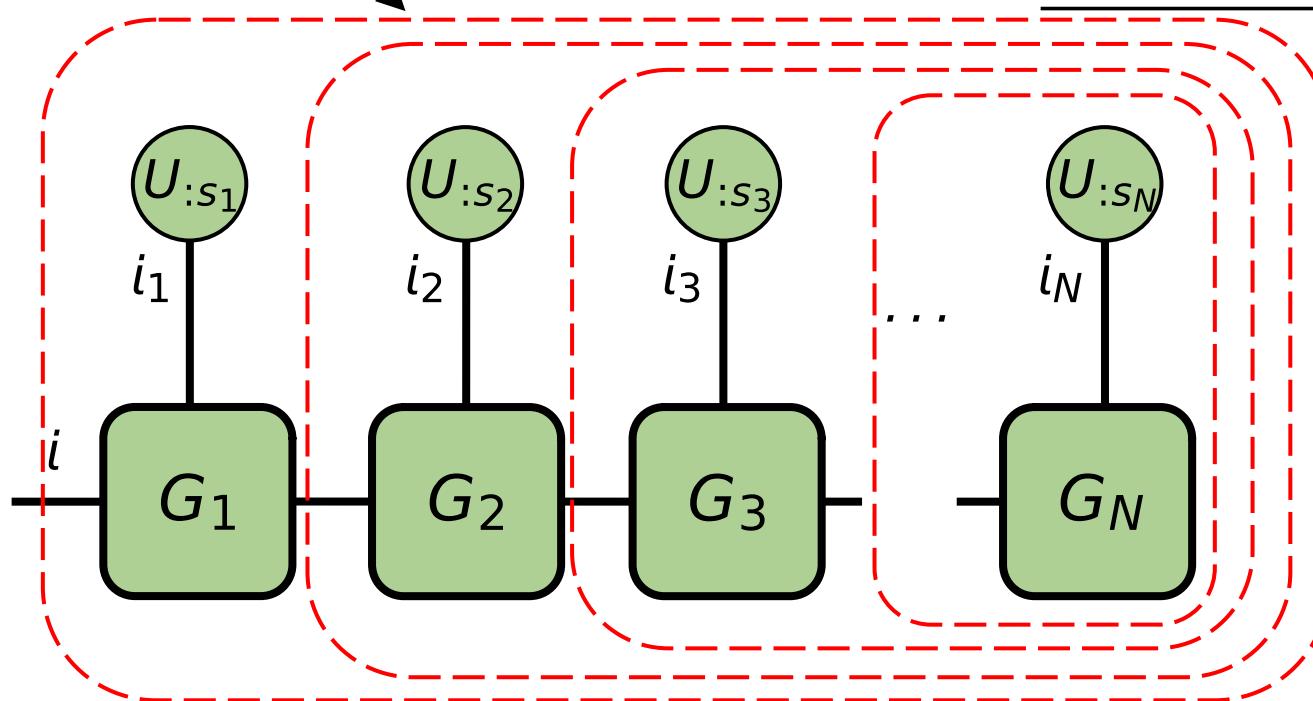
Derivative function decomposition method introduced in

Ryzhakov, G., & Oseledets, I. (2023). «Constructive TT-representation of the tensors given as index interaction functions with applications». The Eleventh International Conference on Learning Representations

Single input, arbitrary output

order of
evaluation

A universal recipe for single Fock input
and arbitrary Fock basis output



only matrix by vector multiplication

input: \mathbf{s} output: $L[i]$

for full output basis:
 $O(N^{M-1+N})$

↓
equivalent to SLOS

Arbitrary input, arbitrary output

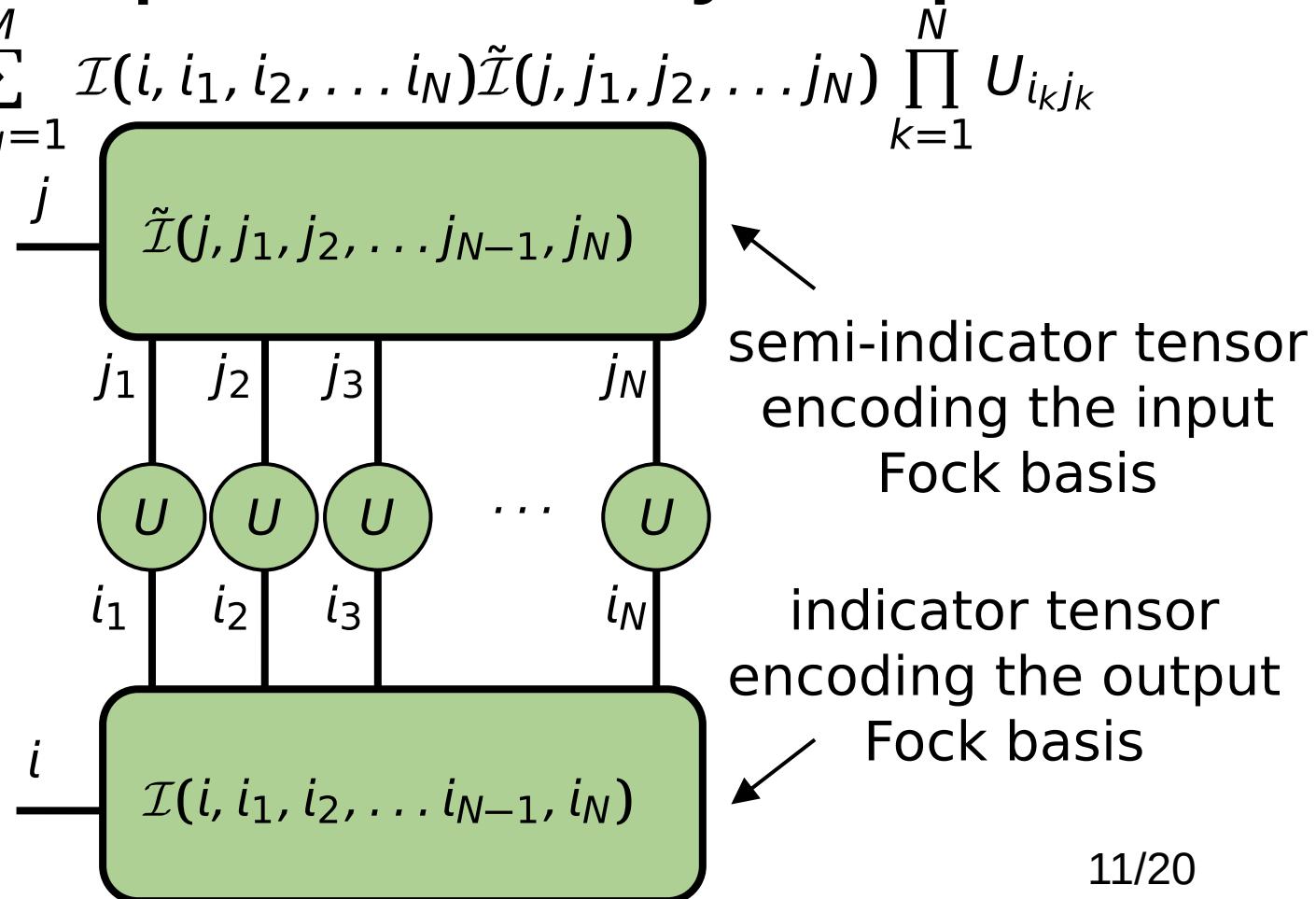
$$U_{ts} \sim \sum_{i_1 j_1=1}^M \sum_{i_2 j_2=1}^M \cdots \sum_{i_N j_N=1}^M \mathcal{I}(i, i_1, i_2, \dots, i_N) \tilde{\mathcal{I}}(j, j_1, j_2, \dots, j_N) \prod_{k=1}^N U_{i_k j_k}$$

$$J[j] = \{s_1, s_2, \dots, s_N\}$$

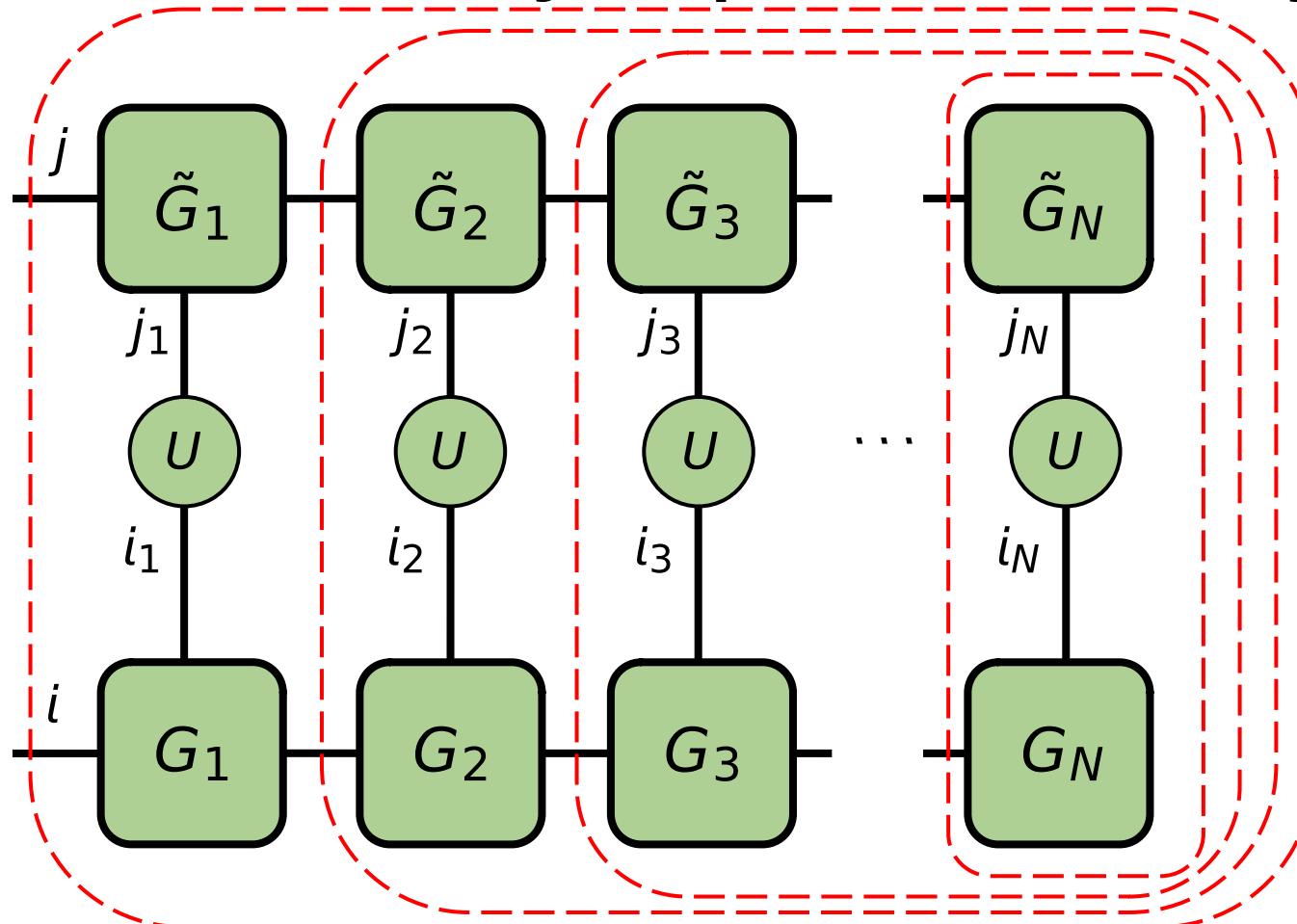
input set of assignment lists

output set of assignment lists

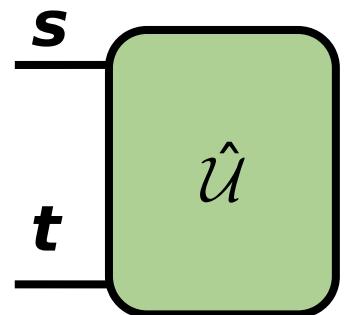
$$L[i] = \{t_1, t_2, \dots, t_N\}$$



Arbitrary input, arbitrary output



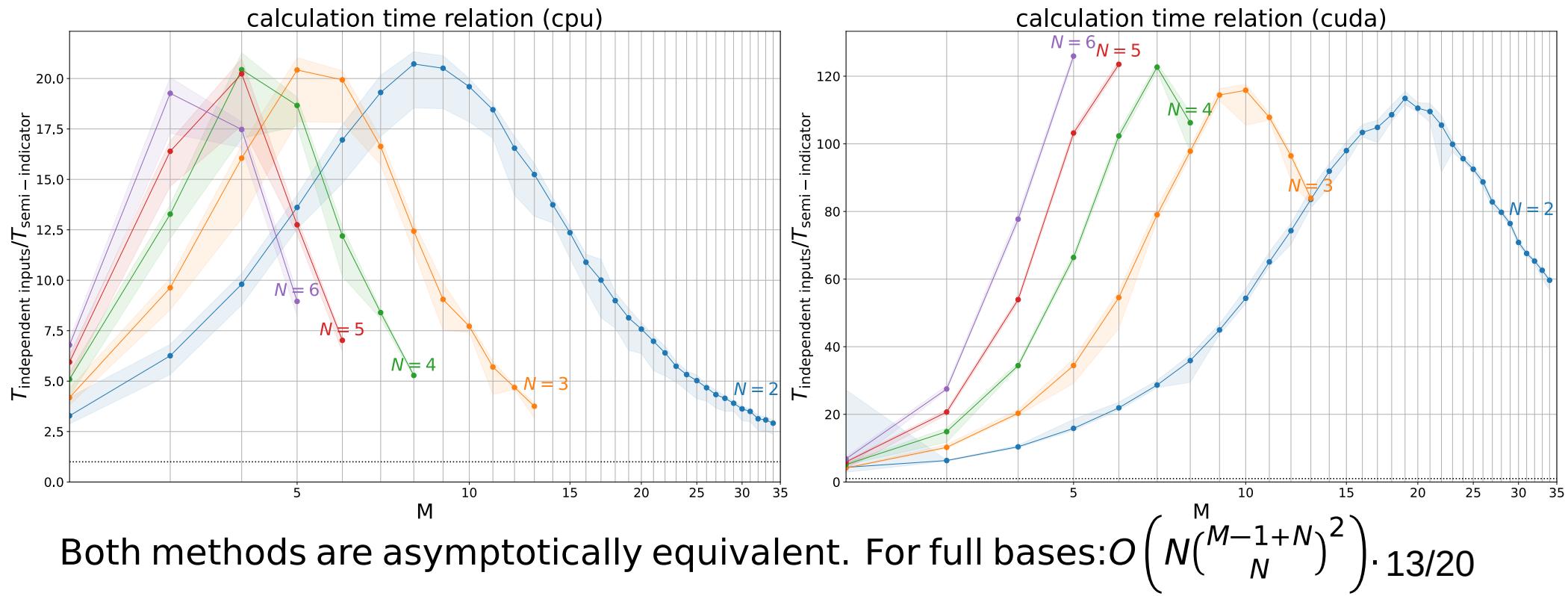
matrix of transformation
amplitudes



for full output
and input basis:
 $O\left(N\binom{M-1+N}{N}^2\right)$

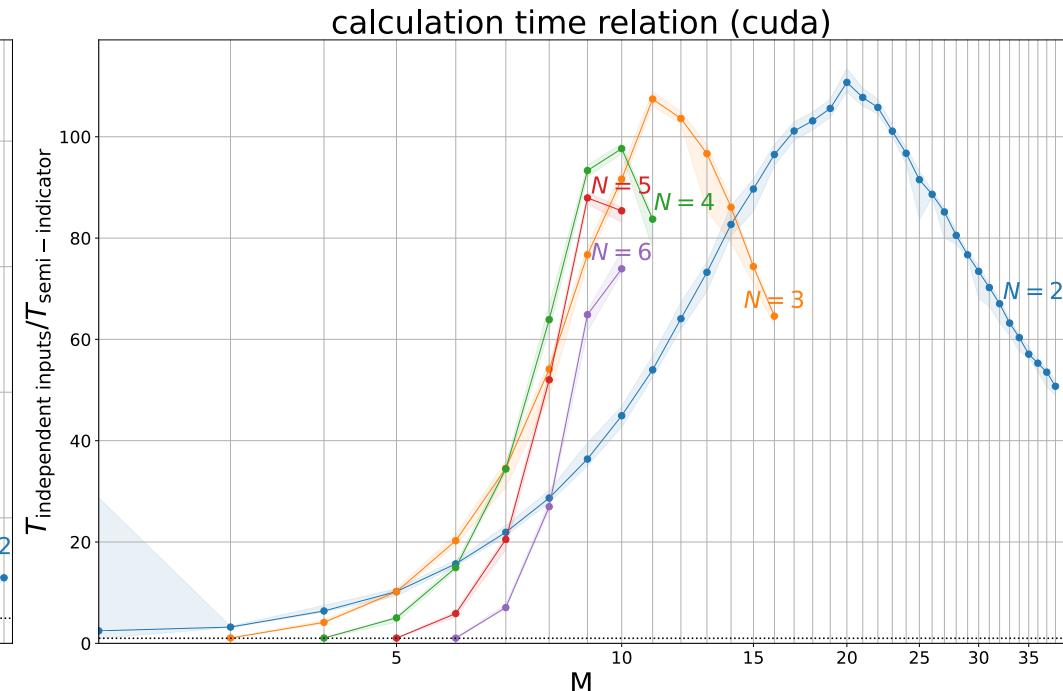
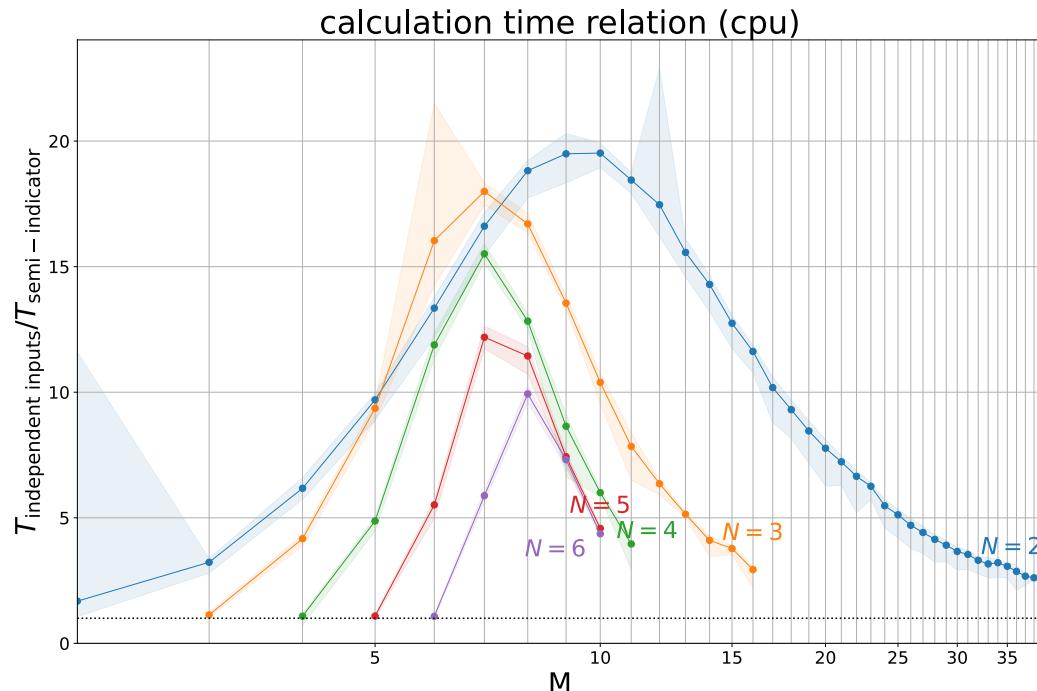
Numerical comparison

How faster is it to calculate transformation amplitudes with the semi-indicator tensor than to calculate each input separately for full bases?



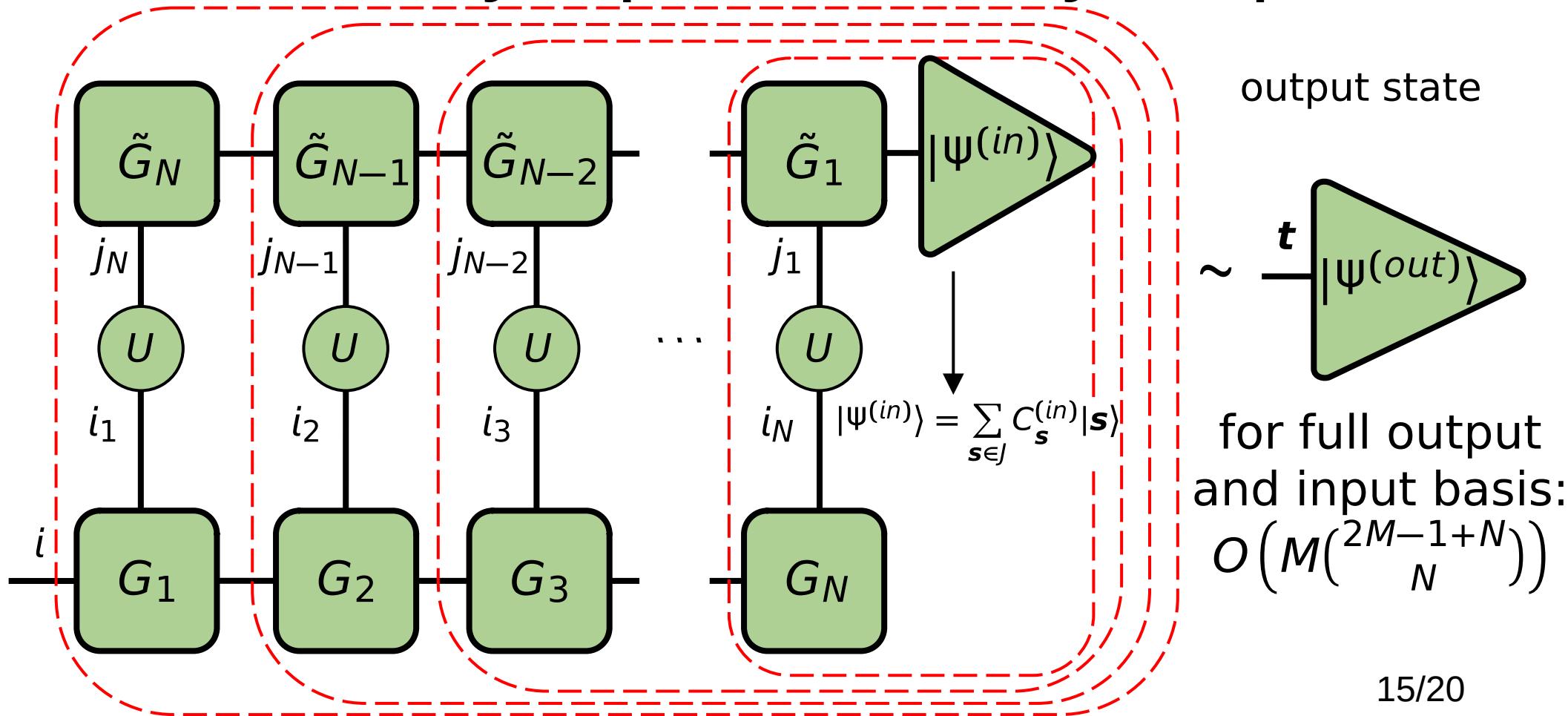
Numerical comparison

How faster is it to calculate transformation amplitudes with the semi-indicator tensor than to calculate each input separately for unbunched bases (assignment lists have no repetitions)?



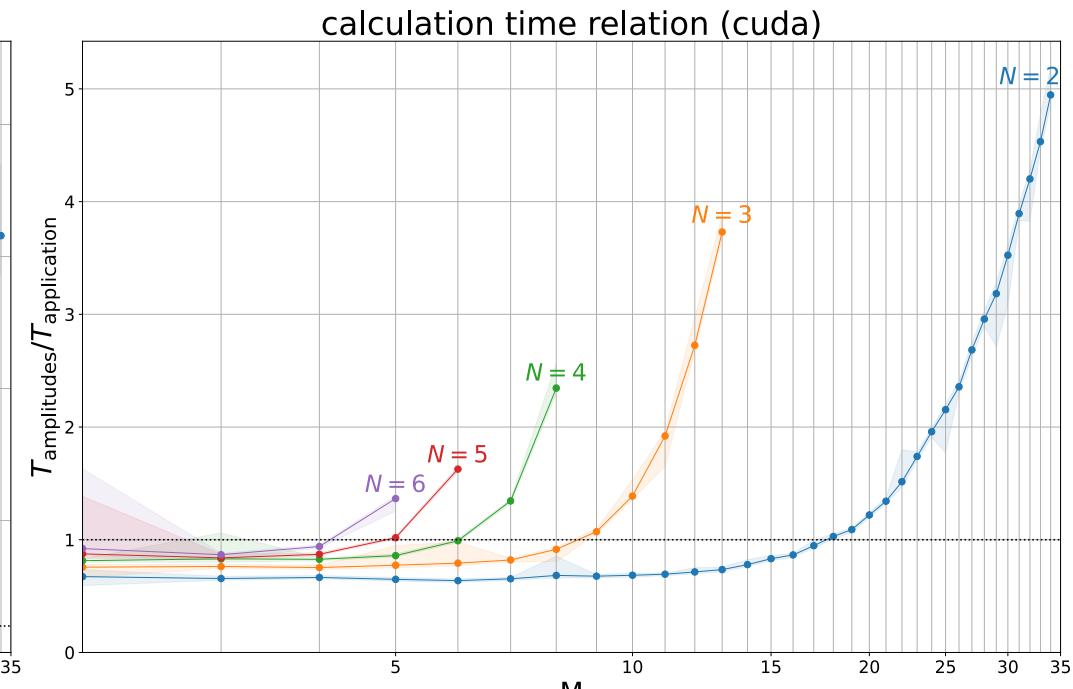
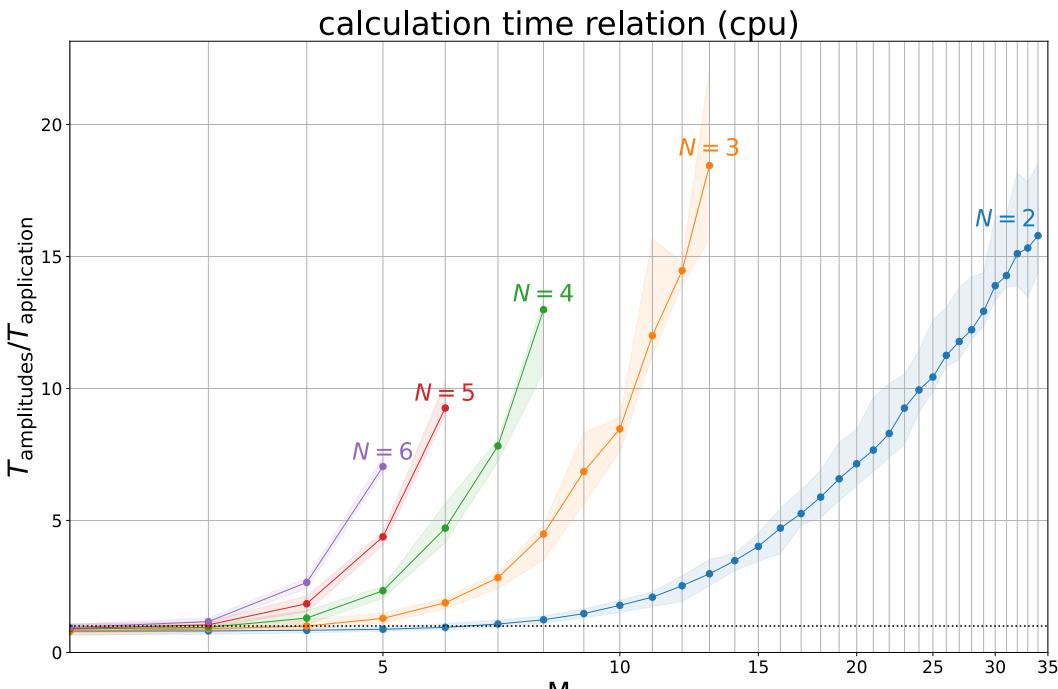
Both methods are asymptotically equivalent.

Arbitrary input, arbitrary output



Numerical comparison

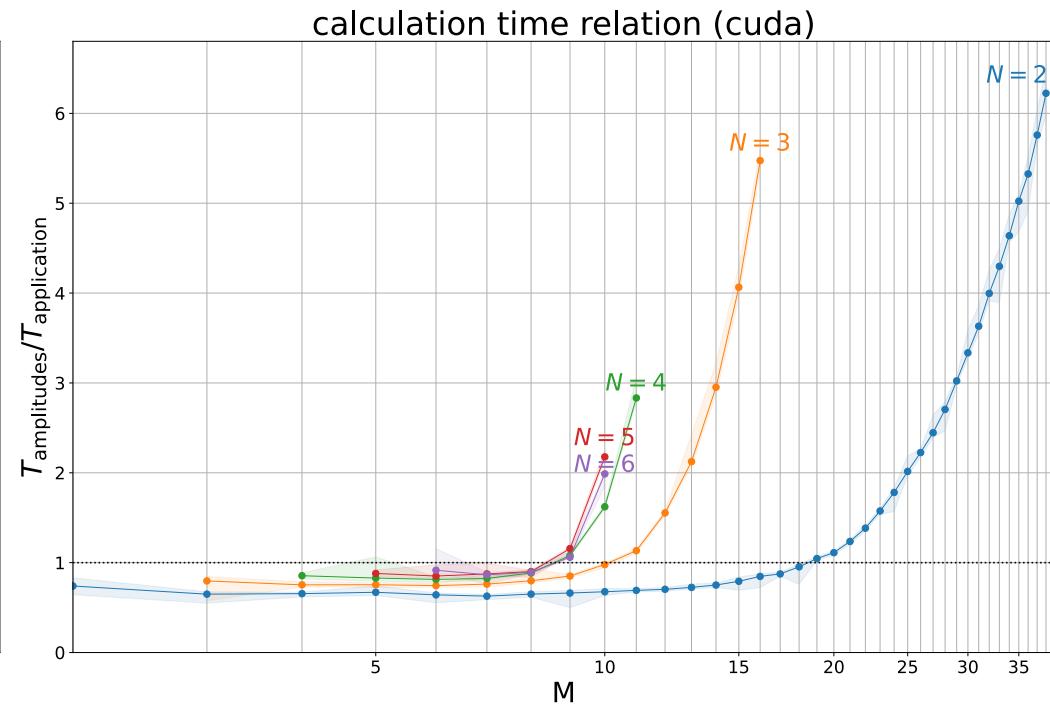
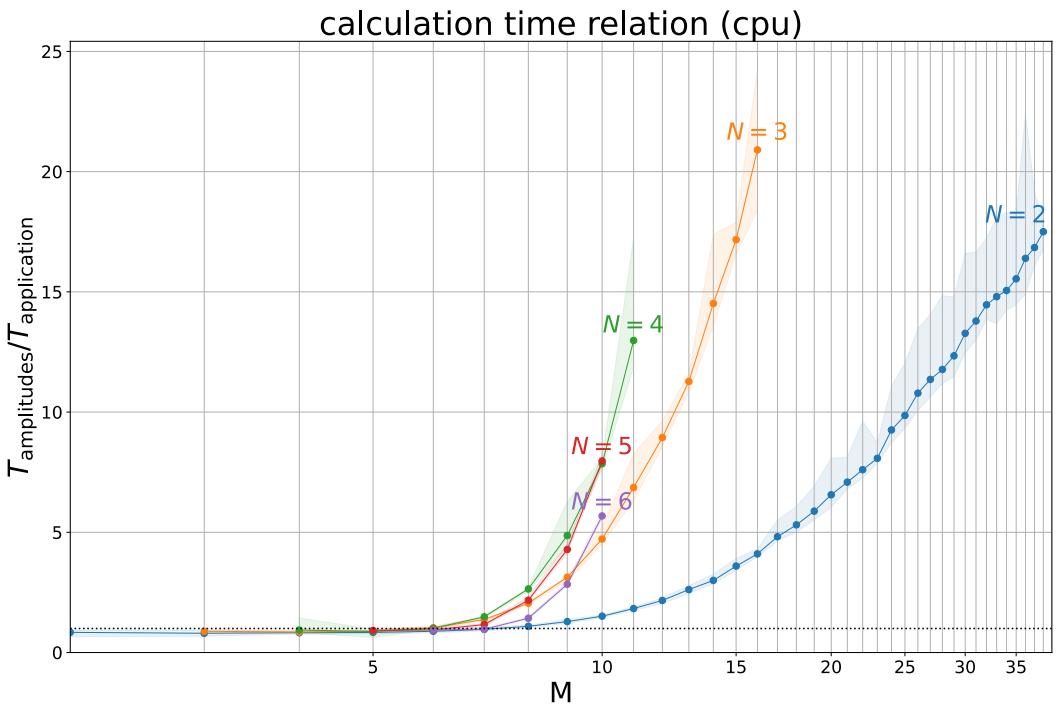
How faster is it to calculate all the transformation amplitudes compared to calculating the application of the transformation for full bases?



For full bases: $O\left(N\binom{M-1+N}{N}^2/M\binom{2M-1+N}{N}\right)$

Numerical comparison

How faster is it to calculate all the transformation amplitudes compared to calculating the application of the transformation for unbunched bases?



Possible generalization

Other quantities involving a sum over permutations

Distinguishable photons:

$$S_{ij} = \langle \phi_i | \phi_j \rangle$$

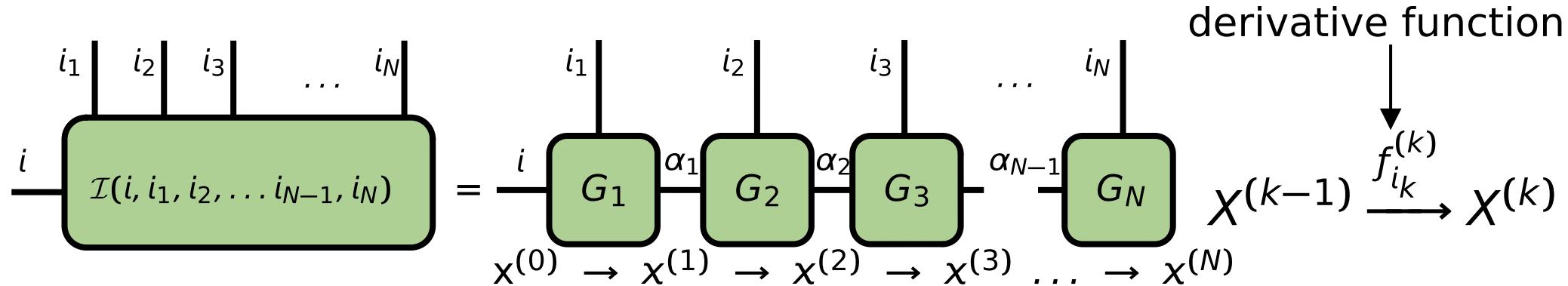
$$\mathcal{P}(\mathbf{t}|\mathbf{s}) = \sum_{\sigma, \tau \in S_N} \prod_{i=1}^N S_{\sigma_i \tau_i} [\bar{U}^{\mathbf{ts}}]_{i\sigma_i} [U^{\mathbf{ts}}]_{i\tau_i}$$

Gaussian boson sampling:

$$\mathcal{P}(\mathbf{s}) = \frac{\text{haf}[A^{\mathbf{s}}]}{\sqrt{\det[\sigma]} \mathbf{s}!}$$

$$\text{haf}[A] = \frac{1}{M!2^M} \sum_{\sigma \in S_{2M}} \prod_{i=1}^M A_{\sigma_{2i-1} \sigma_{2i}}$$

Derivative function decomposition



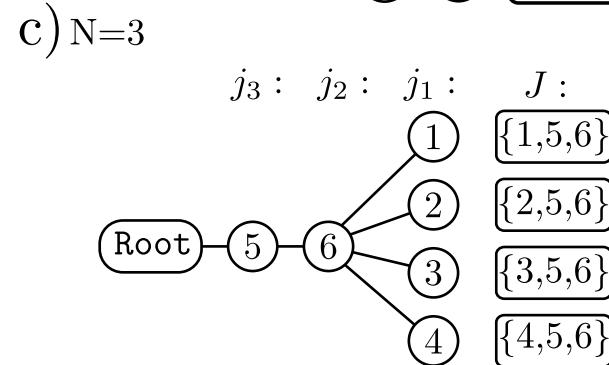
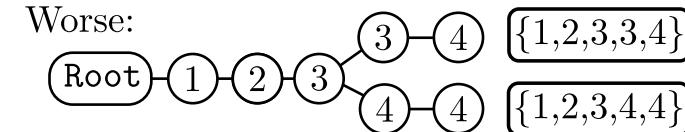
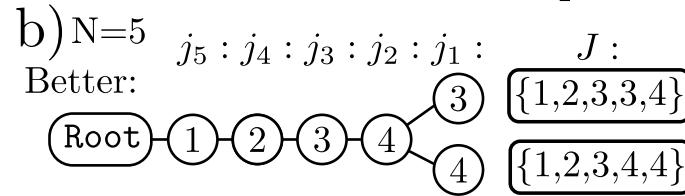
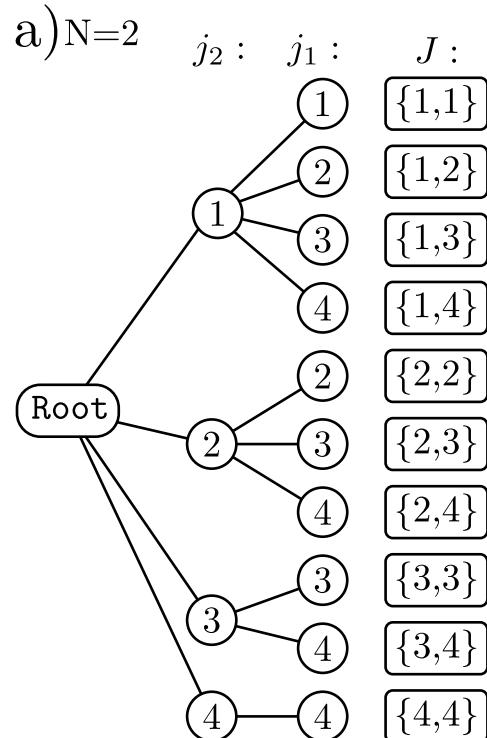
$$x^{(0)} \sim L, x^{(0)} = \{T_1, T_2, T_3, \dots, T_M\} \sim L[i]$$

$$\alpha_{k-1} = \frac{1}{1, |X^{(k-1)}|}, \alpha_k = \frac{1}{1, |X^{(k)}|}$$

for $G_k(\alpha_{k-1}; i_k; \alpha_k) = 0$ or $1; \forall 1 \leq k \leq N$:

$$x^{(k)} = f_{i_k}^{(k)}(x^{(k-1)}) = \begin{cases} x^{(k-1)}[i_k] \leftarrow x^{(k-1)}[i_k] - 1; & x^{(k-1)}, x[i_k] > 0, \\ & \text{None,} & \text{else} \end{cases}$$

Derivative function decomposition



$$x^{(k)} = \tilde{f}_{j_k}^{(k)}(x^{(k-1)}) = \begin{cases} x^{(k-1)}.parent, & \text{if } x^{(k-1)}.key = j_k, \\ \text{None, else} & \end{cases}, \quad \forall 1 \leq k \leq N.$$